A CURVATURE CRITERION FOR MONOTONICITY OF DOMAINS

J. Mensah

October 27, 2025

Abstract

We extend the definition of monotonicity given in [PS85] to higher dimensional domains and establish a criterion which implies that a given domain is monotone with respect to at least one direction in terms of an inequality involving the total absolute Gauss-Kronecker curvature of its boundary. As a corollary of this result, we show that all polygons with five or fewer sides are monotone.

1. Introduction

Let Ω be an open polygon in the plane, and let $\theta \in \mathbb{S}^1$ be a direction vector. We say that Ω is *monotone* with respect to θ if its intersection with every line ℓ orthogonal to θ is either empty or an interval in ℓ . Intuitively, this means one can completely "hatch" the region with a pen without having to lift the pen for any hatch line, as shown in Figure 1. Monotonicity is a kind of generalization of convexity: if Ω is convex, then it is automatically monotone with respect to all directions. Typically, this notion is defined for polygons in terms of the number of crossings of a line with the boundary of the polygon, as done in [PS85]. The name is derived from the following fact (see [PS81]): if Γ is polygon monotone with respect to a direction θ , then the edges of Γ may be split into two continguous chains of vertices v_1, \ldots, v_n and w_1, \ldots, w_m such that $\langle v_i, \theta \rangle$ and $\langle w_i, \theta \rangle$ are monotone in i and j respectively.

The definition of monotonicity may be extended to higher-dimensional domains (open sets) as follows. If $\Omega \subseteq \mathbb{R}^n$ is a bounded domain and $\theta \in \mathbb{S}^{n-1}$, we say that Ω is monotone with respect to θ if its intersection with every hyperplane H orthogonal to θ is either empty or a homeomorphic to the (n-1)-ball \mathbb{B}^n . In this note, we establish criteria involving the boundary of a domain Ω which imply that it is monotone with respect to some direction.

1.1. Preliminaries and Conventions

We establish some useful notation, terminology, and conventions. Let \mathbb{RP}^{n-1} be the quotient of \mathbb{S}^{n-1} under the involution map $x \mapsto -x$ for all $x \in \mathbb{S}^{n-1}$. Since a domain $\Omega \subseteq \mathbb{R}^n$ is monotone with respect to a direction $\theta \in \mathbb{S}^{n-1}$ if and only if it is monotone with respect to $-\theta$, we may say that Ω is monotone with respect to the

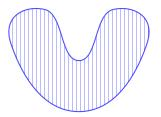




Figure 1: The V-shaped domain above is monotonic horizontally (blue, vertical hatch lines), but not vertically (red, horizonal hatch lines).

direction $[\theta] \in \mathbb{RP}^{n-1}$. The involution map on the sphere is an isometry, so the quotient carries an induced Riemannian metric. Denote the quotient map by $\rho \colon \mathbb{S}^{n-1} \to \mathbb{RP}^{n-1}$, which is a double cover and a local isometry.

For an smooth hypersurface $M \subseteq \mathbb{R}^n$ bounding a domain, the Gauss map is a surjective map $n \colon M \to \mathbb{S}^{n-1}$ which maps a point $p \in M$ to the (outward) normal vector at p. By composing with the double cover, we obtain a map $\nu \colon M \to \mathbb{RP}^{n-1}$ which we refer to as the *projectivized* Gauss map. The Gauss-Kronecker curvature of M is the unique real function K such that

$$n^* \omega_{\mathbb{S}^{n-1}} = K \cdot \omega_M, \tag{1.1}$$

where $\omega_{\mathbb{S}^{n-1}}$ and ω_M are the volume forms of \mathbb{S}^{n-1} and M, respectively. The absolute Gauss-Kronecker curvature is given by Jacobian

$$|K(p)| = \sqrt{\det(\mathrm{d}n_p^* \circ \mathrm{d}n_p)},\tag{1.2}$$

where $[\cdot]^*$ is the adjoint of a linear map between inner product spaces.

Finally, if Γ is a nondegenerate polygon, we use the convention that all exterior angles are given in the range $(-\pi, \pi)$.

2. Monotone Domains

The main theorems of this paper rely on the following lemma which is analogous to [PS81, Theorem 1], which concerns polygons in the plane. Although the result we give fails to be a complete characterization of monotonicity in a given direction, it is enough for the purposes of later arguments.

Lemma 2.1. Let $\Omega \subseteq \mathbb{R}^n$ be a bounded domain with smooth boundary Γ , and let $\nu \colon \Gamma \to \mathbb{RP}^n$ be the projectivized Gauss map. If $|\nu^{-1}\{[\theta]\}| = 2$ for some $[\theta] \in \mathbb{RP}^{n-1}$, then Ω is monotone with respect to $[\theta]$.

Proof. Consider the projection $\pi \colon \mathbb{R}^n \to \mathbb{R}$ defined by $\pi(x) = \langle x, \theta \rangle$ and let $h = \pi|_{\Gamma}$. At a critical point p of h, we have

$$\mathrm{d}h_n(v) = \langle v, \theta \rangle = 0$$

for all $v \in T_p\Gamma$, which occurs if and only if $\nu(p) = [\theta]$. Since Γ is compact and not contained in a line, h attains a maximum and minimum at distinct points $p_+, p_- \in \Gamma$. By hypothesis, the preimage of $[\theta]$ under ν contains two elements, so there are no other critical values in $(\min h, \max h)$. By [Kam15, Theorem A], $h^{-1}\{t\}$ is homeomorphic to \mathbb{S}^{n-2} whenever t is not an extreme value of h. Therefore, by the generalized Schoenflies theorem (see [Put25]), each slice $\Omega \cap \pi^{-1}\{t\}$ is homeomorphic to \mathbb{B}^{n-1} whenever it is nonempty. The conclusion follows.

We now prove the main theorems of the paper.

Theorem 2.2. Let $\Omega \subseteq \mathbb{R}^n$ be a bounded domain with smooth boundary Γ . If the total absolute Gauss-Kronecker curvature satisfies $\int_{\Gamma} |K| d\Gamma < 2 \operatorname{vol}(\mathbb{S}^{n-1})$, then Ω is monotone with respect to some direction.

Proof. Let $n: \Gamma \to \mathbb{S}^{n-1}$ be the Gauss map and $\nu = \rho \circ n$, where $\rho: \mathbb{S}^{n-1} \to \mathbb{RP}^{n-1}$ is the projection map. Since ρ is a local isometry, the absolute Gauss-Kronecker curvature at a point $p \in \Gamma$ is given by the Jacobian

$$|K(p)| = \sqrt{\det(\mathrm{d}n_p^* \circ \mathrm{d}n_p)} = \sqrt{\det(\mathrm{d}\nu_p^* \circ \mathrm{d}\nu_p)} = |\mathrm{J}_p\nu|. \tag{2.1}$$

Define $\mu \colon \mathbb{RP}^{n-1} \to \mathbb{N}_{>0}$ by $\mu([\theta]) = |\nu^{-1}\{[\theta]\}|$. Then by (2.1) and the smooth coarea formula [Cha06], we have

$$\frac{1}{\operatorname{vol}(\mathbb{RP}^{n-1})} \int_{\mathbb{RP}^{n-1}} \mu \, \mathrm{d}\mathbb{RP}^{n-1} = \frac{1}{\frac{1}{2} \operatorname{vol}(\mathbb{S}^{n-1})} \int_{\Gamma} |K| \, \mathrm{d}\Gamma < 4, \tag{2.2}$$

so the average multiplicity of a direction $[\theta] \in \mathbb{RP}^{n-1}$ is strictly bounded above by 4. Note that $\deg_2(\nu) = 0$ since ν factors through a double cover. It follows that μ takes on positive even values almost everywhere, so such an average is attained only if $\mu([\theta]) = 2$ for some $\theta \in \mathbb{S}^{n-1}$. The conclusion follows from Lemma 2.1.

By applying a standard smoothing argument, one may obtain an analogous result for polygons in the plane.

Theorem 2.3. Let $\Omega \subseteq \mathbb{R}^2$ be a domain with polygonal boundary Γ . If the sum of the absolute values of the exterior angles of Γ is less than 4π , then Ω is monotone with respect to some direction.

Proof. Let ϕ_1, \dots, ϕ_n be the exterior angles of Γ . By "rounding" each of the corners of Ω , one may obtain a sequence $\Omega_i \to \Omega$ of domains with smooth boundaries Γ_i such that the multiplicities $\mu_i \colon \mathbb{RP}^1 \to \mathbb{N}_{>0}$ of the projectivized Gauss maps do not vary with i, and

$$\int_{\Gamma_i} |K| \, \mathrm{d}\Gamma_i = \sum_{k=1}^n |\phi_k|. \tag{2.3}$$

It follows from the proof of Theorem 2.2 that there exists a consistent direction $[\theta]$ for which each Ω_i is monotone. Then for a line ℓ normal to $[\theta]$, the slices $\Omega_i \cap \ell$ are intervals which converge to $\Omega \cap \ell$. Since the limit of a sequence of intervals is also an interval

and $\Omega \cap \ell$ is open in ℓ , it must either be empty or homeomorphic to \mathbb{B}^1 . The conclusion follows.

As a corollary, one may show that every polygon with five or fewer sides is monotone in at least one direction.

Corollary 2.4. Let $\Omega \subseteq \mathbb{R}^2$ be a domain with n-sided polygonal boundary. If $n \leq 5$, then Ω is monotone with respect to some direction.

Proof. Let $\theta_1, \dots, \theta_n \in (-\pi, \pi)$ be the exterior angles of the boundary polygon. Suppose that j angles are nonnegative and k angles are negative. Since the sum of exterior angles is 2π , we have

$$\sum_{i=1}^{n} |\theta_i| = \sum_{\theta_i \geq 0} \theta_i - \sum_{\theta_i < 0} \theta_i < 2\pi \min(j-1, k+1) \leq 4\pi, \tag{2.4}$$

so Ω is monotone with respect to some direction.

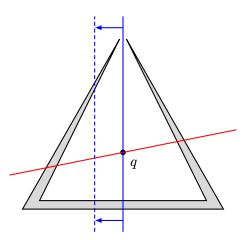


Figure 2: A hexagon which is not monotonic with respect to any direction. Lines through the centroid q may be shifted to intersect the boundary in more than two points.

This result is sharp. For example, the hexagon in Figure 2 is not monotone with respect to any direction. Indeed, any line through q not passing through the "slit" must intersect the boundary in four points. On the other hand, any line through q passing through the slit may be translated left or right to achieve the same result.

References

[Cha06] Isaac Chavel. Riemannian Geometry: A Modern Introduction. Cambridge Studies in Advanced Mathematics. Cambridge University Press, Cambridge, UK, 2 edition, 2006.

- [Kam15] Yasuhiko Kamiyama. On the level set of a function with degenerate minimum point. *International Journal of Mathematics and Mathematical Sciences*, 2015(1):493217, 2015.
- [PS81] Franco P. Preparata and Kenneth J. Supowit. Testing a simple polygon for monotonicity. *Information Processing Letters*, 12(4):161–164, 1981.
- [PS85] Franco P. Preparata and Michael Ian Shamos. Computational Geometry: An Introduction. Monographs in Computer Science. Springer Science+Business Media, New York, NY, USA, 1 edition, 1985.
- [Put25] Andrew Putman. The generalized schoenflies theorem. https://academicweb.nd.edu/~andyp/notes/Schoenflies.pdf, 2025.